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TENSOR DECOMPOSITIONS AND SPARSE LOG-LINEAR MODELS

BY JAMES E. JOHNDROW^{*,1}, ANIRBAN BHATTACHARYA^{†,2}
AND DAVID B. DUNSON^{*,1}

*Duke University** and *Texas A&M University*[†]

Contingency table analysis routinely relies on log-linear models, with latent structure analysis providing a common alternative. Latent structure models lead to a reduced rank tensor factorization of the probability mass function for multivariate categorical data, while log-linear models achieve dimensionality reduction through sparsity. Little is known about the relationship between these notions of dimensionality reduction in the two paradigms. We derive several results relating the support of a log-linear model to nonnegative ranks of the associated probability tensor. Motivated by these findings, we propose a new collapsed Tucker class of tensor decompositions, which bridge existing PARAFAC and Tucker decompositions, providing a more flexible framework for parsimoniously characterizing multivariate categorical data. Taking a Bayesian approach to inference, we illustrate empirical advantages of the new decompositions.

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A LAVA ATTACK ON THE RECOVERY OF SUMS OF DENSE AND SPARSE SIGNALS

BY VICTOR CHERNOZHUKOV, CHRISTIAN HANSEN¹ AND YUAN LIAO

*Massachusetts Institute of Technology, University of Chicago
and University of Maryland*

Common high-dimensional methods for prediction rely on having either a sparse signal model, a model in which most parameters are zero and there are a small number of nonzero parameters that are large in magnitude, or a dense signal model, a model with no large parameters and very many small nonzero parameters. We consider a generalization of these two basic models, termed here a “sparse + dense” model, in which the signal is given by the sum of a sparse signal and a dense signal. Such a structure poses problems for traditional sparse estimators, such as the lasso, and for traditional dense estimation methods, such as ridge estimation. We propose a new penalization-based method, called lava, which is computationally efficient. With suitable choices of penalty parameters, the proposed method strictly dominates both lasso and ridge. We derive analytic expressions for the finite-sample risk function of the lava estimator in the Gaussian sequence model. We also provide a deviation bound for the prediction risk in the Gaussian regression model with fixed design. In both cases, we provide Stein’s unbiased estimator for lava’s prediction risk. A simulation example compares the performance of lava to lasso, ridge and elastic net in a regression example using data-dependent penalty parameters and illustrates lava’s improved performance relative to these benchmarks.

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STATISTICAL GUARANTEES FOR THE EM ALGORITHM: FROM POPULATION TO SAMPLE-BASED ANALYSIS¹

BY SIVARAMAN BALAKRISHNAN^{*,†},
MARTIN J. WAINWRIGHT[†] AND BIN YU[†]

University of California, Berkeley and Carnegie Mellon University[†]*

The EM algorithm is a widely used tool in maximum-likelihood estimation in incomplete data problems. Existing theoretical work has focused on conditions under which the iterates or likelihood values converge, and the associated rates of convergence. Such guarantees do not distinguish whether the ultimate fixed point is a near global optimum or a bad local optimum of the sample likelihood, nor do they relate the obtained fixed point to the global optima of the idealized population likelihood (obtained in the limit of infinite data). This paper develops a theoretical framework for quantifying when and how quickly EM-type iterates converge to a small neighborhood of a given global optimum of the population likelihood. For correctly specified models, such a characterization yields rigorous guarantees on the performance of certain two-stage estimators in which a suitable initial pilot estimator is refined with iterations of the EM algorithm. Our analysis is divided into two parts: a treatment of the EM and first-order EM algorithms at the population level, followed by results that apply to these algorithms on a finite set of samples. Our conditions allow for a characterization of the region of convergence of EM-type iterates to a given population fixed point, that is, the region of the parameter space over which convergence is guaranteed to a point within a small neighborhood of the specified population fixed point. We verify our conditions and give tight characterizations of the region of convergence for three canonical problems of interest: symmetric mixture of two Gaussians, symmetric mixture of two regressions and linear regression with covariates missing completely at random.

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NORMAL APPROXIMATION AND CONCENTRATION OF SPECTRAL PROJECTORS OF SAMPLE COVARIANCE

BY VLADIMIR KOLTCHINSKII¹ AND KARIM LOUNICI²

Georgia Institute of Technology

Let X, X_1, \dots, X_n be i.i.d. Gaussian random variables in a separable Hilbert space \mathbb{H} with zero mean and covariance operator $\Sigma = \mathbb{E}(X \otimes X)$, and let $\hat{\Sigma} := n^{-1} \sum_{j=1}^n (X_j \otimes X_j)$ be the sample (empirical) covariance operator based on (X_1, \dots, X_n) . Denote by P_r the spectral projector of Σ corresponding to its r th eigenvalue μ_r and by \hat{P}_r the empirical counterpart of P_r . The main goal of the paper is to obtain tight bounds on

$$\sup_{x \in \mathbb{R}} \left| \mathbb{P} \left\{ \frac{\|\hat{P}_r - P_r\|_2^2 - \mathbb{E}\|\hat{P}_r - P_r\|_2^2}{\text{Var}^{1/2}(\|\hat{P}_r - P_r\|_2^2)} \leq x \right\} - \Phi(x) \right|,$$

where $\|\cdot\|_2$ denotes the Hilbert–Schmidt norm and Φ is the standard normal distribution function. Such accuracy of normal approximation of the distribution of squared Hilbert–Schmidt error is characterized in terms of so-called effective rank of Σ defined as $\mathbf{r}(\Sigma) = \frac{\text{tr}(\Sigma)}{\|\Sigma\|_\infty}$, where $\text{tr}(\Sigma)$ is the trace of Σ and $\|\Sigma\|_\infty$ is its operator norm, as well as another parameter characterizing the size of $\text{Var}(\|\hat{P}_r - P_r\|_2^2)$. Other results include nonasymptotic bounds and asymptotic representations for the mean squared Hilbert–Schmidt norm error $\mathbb{E}\|\hat{P}_r - P_r\|_2^2$ and the variance $\text{Var}(\|\hat{P}_r - P_r\|_2^2)$, and concentration inequalities for $\|\hat{P}_r - P_r\|_2^2$ around its expectation.

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A GENERAL THEORY OF HYPOTHESIS TESTS AND CONFIDENCE REGIONS FOR SPARSE HIGH DIMENSIONAL MODELS¹

BY YANG NING AND HAN LIU

Cornell University and Princeton University

We consider the problem of uncertainty assessment for low dimensional components in high dimensional models. Specifically, we propose a novel decorrelated score function to handle the impact of high dimensional nuisance parameters. We consider both hypothesis tests and confidence regions for generic penalized M-estimators. Unlike most existing inferential methods which are tailored for individual models, our method provides a general framework for high dimensional inference and is applicable to a wide variety of applications. In particular, we apply this general framework to study five illustrative examples: linear regression, logistic regression, Poisson regression, Gaussian graphical model and additive hazards model. For hypothesis testing, we develop general theorems to characterize the limiting distributions of the decorrelated score test statistic under both null hypothesis and local alternatives. These results provide asymptotic guarantees on the type I errors and local powers. For confidence region construction, we show that the decorrelated score function can be used to construct point estimators that are asymptotically normal and semiparametrically efficient. We further generalize this framework to handle the settings of misspecified models. Thorough numerical results are provided to back up the developed theory.

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A BAYESIAN APPROACH FOR ENVELOPE MODELS

BY KSHITIJ KHARE¹, SUBHADIP PAL AND ZHIHUA SU²

University of Florida

The envelope model is a new paradigm to address estimation and prediction in multivariate analysis. Using sufficient dimension reduction techniques, it has the potential to achieve substantial efficiency gains compared to standard models. This model was first introduced by [Statist. Sinica **20** (2010) 927–960] for multivariate linear regression, and has since been adapted to many other contexts. However, a Bayesian approach for analyzing envelope models has not yet been investigated in the literature. In this paper, we develop a comprehensive Bayesian framework for estimation and model selection in envelope models in the context of multivariate linear regression. Our framework has the following attractive features. First, we use the matrix Bingham distribution to construct a prior on the orthogonal basis matrix of the envelope subspace. This prior respects the manifold structure of the envelope model, and can directly incorporate prior information about the envelope subspace through the specification of hyperparameters. This feature has potential applications in the broader Bayesian sufficient dimension reduction area. Second, sampling from the resulting posterior distribution can be achieved by using a block Gibbs sampler with standard associated conditionals. This in turn facilitates computationally efficient estimation and model selection. Third, unlike the current frequentist approach, our approach can accommodate situations where the sample size is smaller than the number of responses. Lastly, the Bayesian approach inherently offers comprehensive uncertainty characterization through the posterior distribution. We illustrate the utility of our approach on simulated and real datasets.

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MONGE–KANTOROVICH DEPTH, QUANTILES, RANKS AND SIGNS

BY VICTOR CHERNOZHUKOV^{*,1}, ALFRED GALICHON^{†,2},
MARC HALLIN^{‡,3} AND MARC HENRY^{§,4}

Massachusetts Institute of Technology^{*}, *New York University*[†],
Université libre de Bruxelles[‡] and *Pennsylvania State University*[§]

We propose new concepts of statistical depth, multivariate quantiles, vector quantiles and ranks, ranks and signs, based on canonical transportation maps between a distribution of interest on \mathbb{R}^d and a reference distribution on the d -dimensional unit ball. The new depth concept, called *Monge–Kantorovich depth*, specializes to halfspace depth for $d = 1$ and in the case of spherical distributions, but for more general distributions, differs from the latter in the ability for its contours to account for non-convex features of the distribution of interest. We propose empirical counterparts to the population versions of those Monge–Kantorovich depth contours, quantiles, ranks, signs and vector quantiles and ranks, and show their consistency by establishing a uniform convergence property for empirical (forward and reverse) transport maps, which is the main theoretical result of this paper.

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IDENTIFYING THE NUMBER OF FACTORS FROM SINGULAR VALUES OF A LARGE SAMPLE AUTO-COVARIANCE MATRIX¹

BY ZENG LI, QINWEN WANG AND JIANFENG YAO

University of Hong Kong

Identifying the number of factors in a high-dimensional factor model has attracted much attention in recent years and a general solution to the problem is still lacking. A promising ratio estimator based on singular values of lagged sample auto-covariance matrices has been recently proposed in the literature with a reasonably good performance under some specific assumption on the strength of the factors. Inspired by this ratio estimator and as a first main contribution, this paper proposes a complete theory of such sample singular values for both the factor part and the noise part under the large-dimensional scheme where the dimension and the sample size proportionally grow to infinity. In particular, we provide an exact description of the phase transition phenomenon that determines whether a factor is strong enough to be detected with the observed sample singular values. Based on these findings and as a second main contribution of the paper, we propose a new estimator of the number of factors which is strongly consistent for the detection of all significant factors (which are the only theoretically detectable ones). In particular, factors are assumed to have the minimum strength above the phase transition boundary which is of the order of a constant; they are thus not required to grow to infinity together with the dimension (as assumed in most of the existing papers on high-dimensional factor models). Empirical Monte-Carlo study as well as the analysis of stock returns data attest a very good performance of the proposed estimator. In all the tested cases, the new estimator largely outperforms the existing estimator using the same ratios of singular values.

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CONSISTENCY OF SPECTRAL HYPERGRAPH PARTITIONING UNDER PLANTED PARTITION MODEL

BY DEBARGHYA GHOSHDASTIDAR AND AMBEDKAR DUKKIPATI

Indian Institute of Science

Hypergraph partitioning lies at the heart of a number of problems in machine learning and network sciences. Many algorithms for hypergraph partitioning have been proposed that extend standard approaches for graph partitioning to the case of hypergraphs. However, theoretical aspects of such methods have seldom received attention in the literature as compared to the extensive studies on the guarantees of graph partitioning. For instance, consistency results of spectral graph partitioning under the stochastic block model are well known. In this paper, we present a planted partition model for sparse random nonuniform hypergraphs that generalizes the stochastic block model. We derive an error bound for a spectral hypergraph partitioning algorithm under this model using matrix concentration inequalities. To the best of our knowledge, this is the first consistency result related to partitioning nonuniform hypergraphs.

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ORACLE INEQUALITIES FOR NETWORK MODELS AND SPARSE GRAPHON ESTIMATION

BY OLGA KLOPP^{*,1}, ALEXANDRE B. TSYBAKOV^{†,2} AND
NICOLAS VERZELEN^{‡,3}

Université Paris Ouest^{}, ENSAE, UMR CNRS 9194[†] and
INRA, UMR 729, MISTEA[‡]*

Inhomogeneous random graph models encompass many network models such as stochastic block models and latent position models. We consider the problem of statistical estimation of the matrix of connection probabilities based on the observations of the adjacency matrix of the network. Taking the stochastic block model as an approximation, we construct estimators of network connection probabilities—the ordinary block constant least squares estimator, and its restricted version. We show that they satisfy oracle inequalities with respect to the block constant oracle. As a consequence, we derive optimal rates of estimation of the probability matrix. Our results cover the important setting of sparse networks. Another consequence consists in establishing upper bounds on the minimax risks for graphon estimation in the L_2 norm when the probability matrix is sampled according to a graphon model. These bounds include an additional term accounting for the “agnostic” error induced by the variability of the latent unobserved variables of the graphon model. In this setting, the optimal rates are influenced not only by the bias and variance components as in usual nonparametric problems but also include the third component, which is the agnostic error. The results shed light on the differences between estimation under the empirical loss (the probability matrix estimation) and under the integrated loss (the graphon estimation).

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APPROXIMATE GROUP CONTEXT TREE

BY ALEXANDRE BELLONI AND ROBERTO I. OLIVEIRA¹

*The Fuqua School of Business
Duke University and IMPA*

We study a variable length Markov chain model associated with a group of stationary processes that share the same context tree but each process has potentially different conditional probabilities. We propose a new model selection and estimation method which is computationally efficient. We develop oracle and adaptivity inequalities, as well as model selection properties, that hold under continuity of the transition probabilities and polynomial β -mixing. In particular, model misspecification is allowed.

These results are applied to interesting families of processes. For Markov processes, we obtain uniform rate of convergence for the estimation error of transition probabilities as well as perfect model selection results. For chains of infinite order with complete connections, we obtain explicit uniform rates of convergence on the estimation of conditional probabilities, which have an explicit dependence on the processes' continuity rates. Similar guarantees are also derived for renewal processes.

Our results are shown to be applicable to discrete stochastic dynamic programming problems and to dynamic discrete choice models. We also apply our estimator to a linguistic study, based on recent work by Galves et al. [*Ann. Appl. Stat.* **6** (2012) 186–209], of the rhythmic differences between Brazilian and European Portuguese.

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FLEXIBLE RESULTS FOR QUADRATIC FORMS WITH APPLICATIONS TO VARIANCE COMPONENTS ESTIMATION

BY LEE H. DICKER¹ AND MURAT A. ERDOGDU

Rutgers University and Stanford University

We derive convenient uniform concentration bounds and finite sample multivariate normal approximation results for quadratic forms, then describe some applications involving variance components estimation in linear random-effects models. Random-effects models and variance components estimation are classical topics in statistics, with a corresponding well-established asymptotic theory. However, our finite sample results for quadratic forms provide additional flexibility for easily analyzing random-effects models in nonstandard settings, which are becoming more important in modern applications (e.g., genomics). For instance, in addition to deriving novel non-asymptotic bounds for variance components estimators in classical linear random-effects models, we provide a concentration bound for variance components estimators in linear models with correlated random-effects and discuss an application involving sparse random-effects models. Our general concentration bound is a uniform version of the Hanson–Wright inequality. The main normal approximation result in the paper is derived using Reinert and Röllin [*Ann. Probab.* (2009) **37** 2150–2173] embedding technique for Stein’s method of exchangeable pairs.

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EXTREME EIGENVALUES OF LARGE-DIMENSIONAL SPIKED FISHER MATRICES WITH APPLICATION

BY QINWEN WANG AND JIANFENG YAO

University of Hong Kong

Consider two p -variate populations, not necessarily Gaussian, with covariance matrices Σ_1 and Σ_2 , respectively. Let S_1 and S_2 be the corresponding sample covariance matrices with degrees of freedom m and n . When the difference Δ between Σ_1 and Σ_2 is of small rank compared to p , m and n , the Fisher matrix $S := S_2^{-1} S_1$ is called a *spiked Fisher matrix*. When p , m and n grow to infinity proportionally, we establish a phase transition for the extreme eigenvalues of the Fisher matrix: a displacement formula showing that when the eigenvalues of Δ (*spikes*) are above (or under) a critical value, the associated extreme eigenvalues of S will converge to some point outside the support of the global limit (LSD) of other eigenvalues (become outliers); otherwise, they will converge to the edge points of the LSD. Furthermore, we derive central limit theorems for those outlier eigenvalues of S . The limiting distributions are found to be Gaussian if and only if the corresponding population spike eigenvalues in Δ are *simple*. Two applications are introduced. The first application uses the largest eigenvalue of the Fisher matrix to test the equality between two high-dimensional covariance matrices, and explicit power function is found under the spiked alternative. The second application is in the field of signal detection, where an estimator for the number of signals is proposed while the covariance structure of the noise is arbitrary.

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